

(12) UK Patent Application (19) GB (11) 2 252 473 (13) A

(43) Date of A publication 05.08.1992

(21) Application No 9207079.6

(22) Date of filing 31.03.1992

(30) Priority data

(31) 9119863

(32) 17.09.1991

(33) GB

(71) Applicant
Radamec EPO Limited

(Incorporated in the United Kingdom)

Bridge Road, Chertsey, Surrey, KT16 8LJ,
United Kingdom

(72) Inventor
Michael John Wolfe

(74) Agent and/or Address for Service
D Young & Co
10 Staple Inn, London, WC1V 7RD, United Kingdom

(51) INT CL⁶
H04N 5/232

(52) UK CL (Edition K)
H4F FCC FD12X FD24 FD26M FD31K FD42C9
FD83X
G2A AAR AG1V AG14A AG16C

(56) Documents cited
GB 2235848 A US 4566036 A

(58) Field of search
UK CL (Edition K) H4F FAA FCC
INT CL⁶ H04N 5/232 5/247 7/18
Online databases : WPI.

(54) Remote control system for robotic camera

(57) In a remote control system for one or more robotic cameras 18, in which a camera can be moved between stored positions, a frame of video is grabbed and stored for each stored camera position, and the stored pictures are displayed on a monitor 26. Selection of a desired camera position is then made by selecting the appropriate displayed picture, for example using a mouse 28, light pen or touch screen. The stored video may be updated each time a camera adopts a particular position.

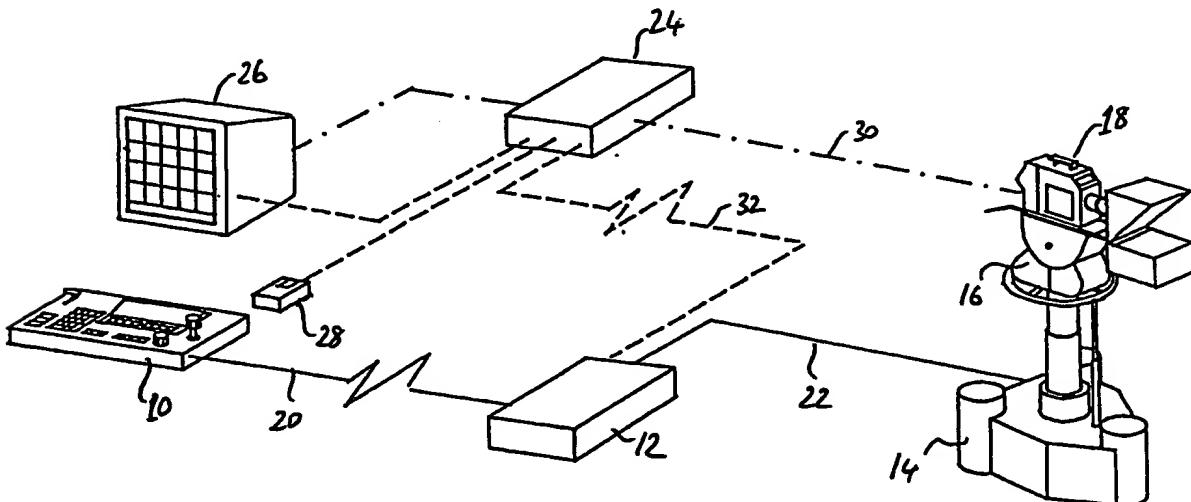


FIG -1-

GB 2 252 473 A

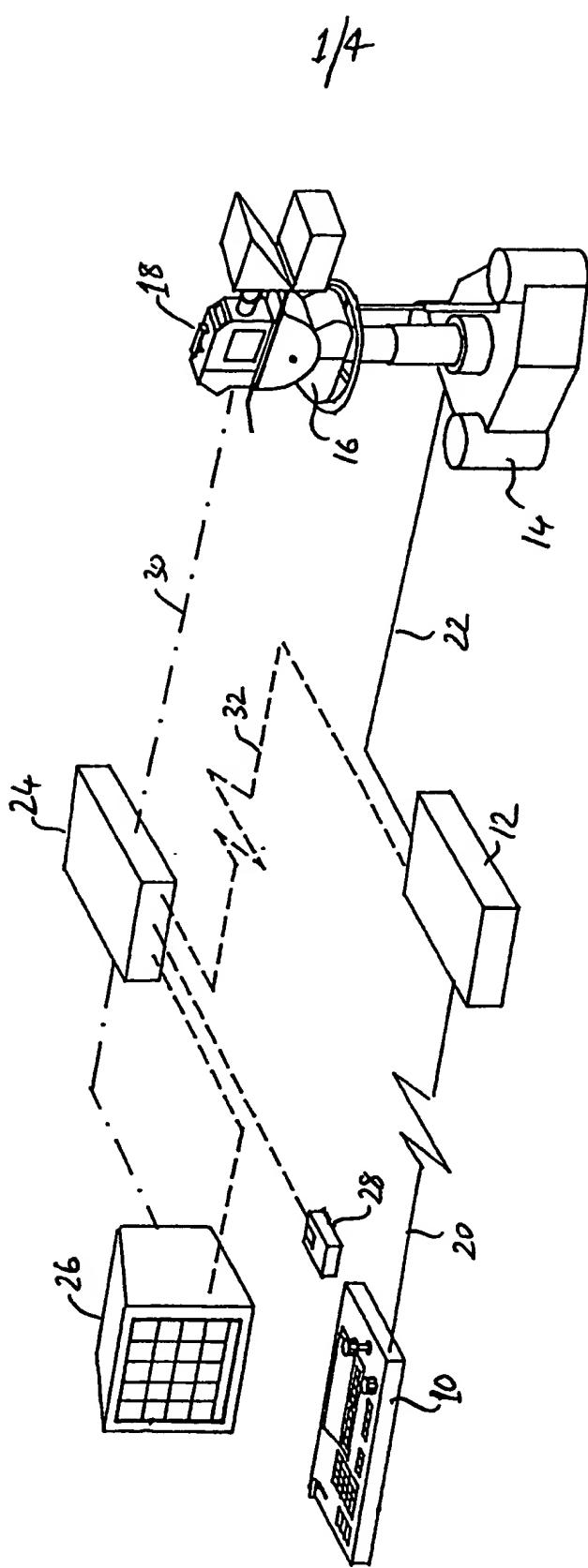


FIG -1-

2/4

Shot A	Shot B	Shot C	Shot D
Shot E	Shot F	Shot G	Shot H
Shot I	Shot J	Shot K	Shot L
Shot M	Shot N	Shot <input type="checkbox"/>	Shot P
CAM 1	CAM 2	CAM 3	CAM 4
STORE	RECALL	SEQUENCE	STEP
			~36

FIG -2-

3/4

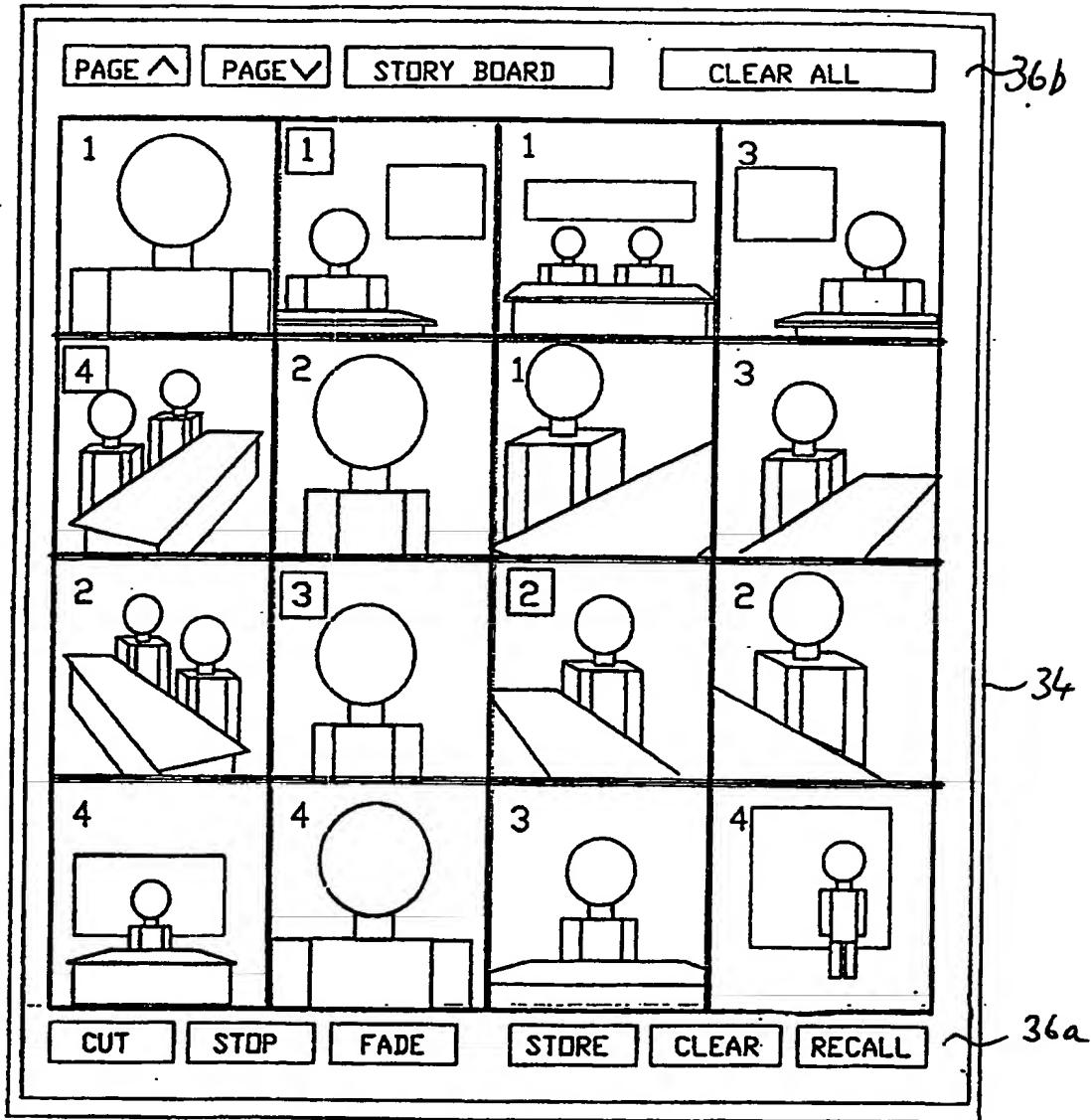


FIG. 3

4/4

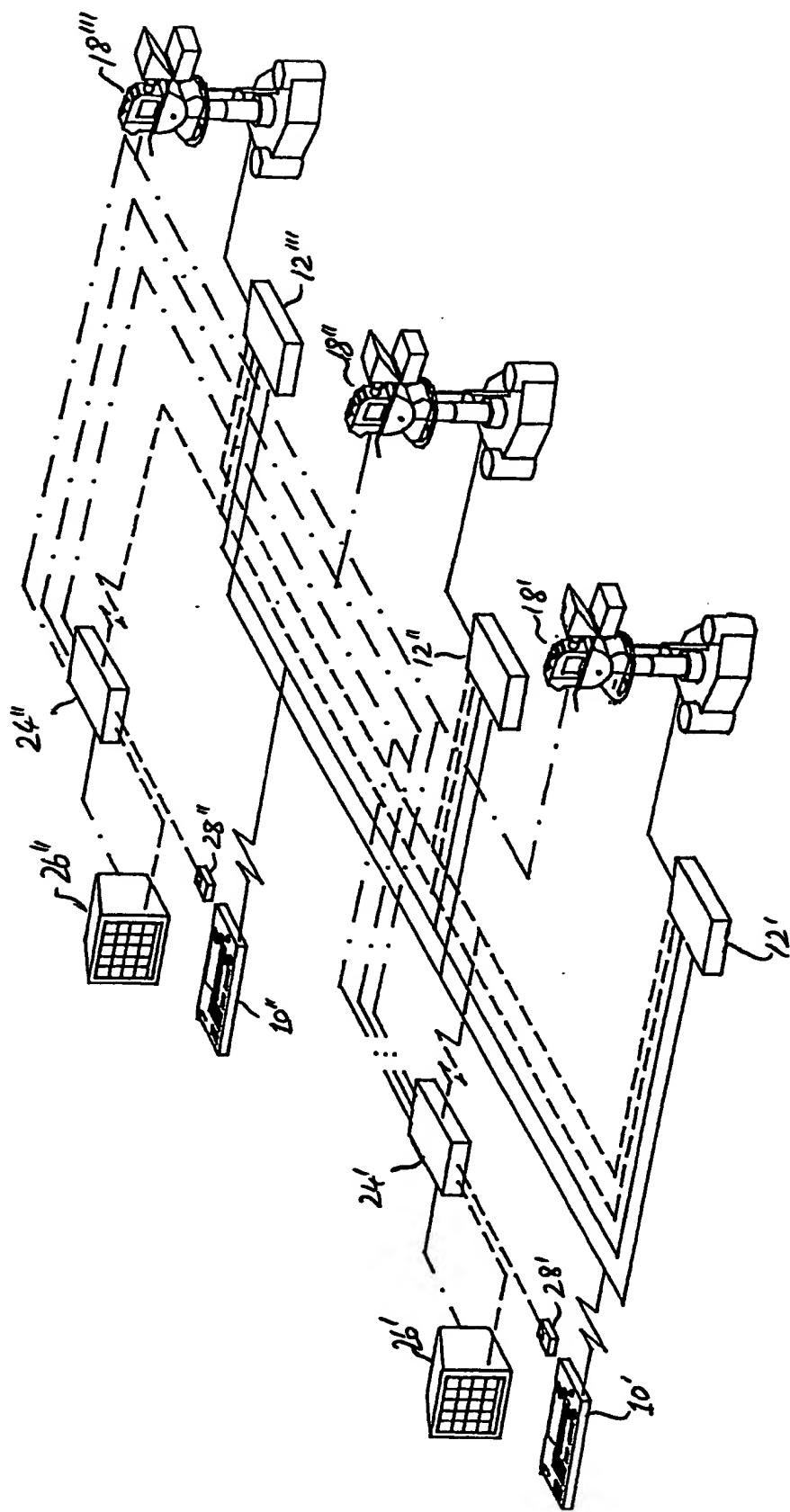


FIG -4-

REMOTE CONTROL SYSTEM FOR ROBOTIC CAMERA

The present invention relates to a remote control system for one or more robotic video cameras.

5 Robotic camera systems are known in which the camera position (e.g. X position, Y position, height, pan angle, tilt angle, zoom setting, focus setting or any combination of these) can be remotely controlled, for example using a controller having a manually operable joystick. A known system available from Radamec EPO Limited, of
10 Chertsey, Surrey, United Kingdom also permits camera positions to be stored with an associated shot number or code. Then, when one of the shot codes is selected, the camera is moved automatically to the respective stored position. Such a system may be utilised in broadcast studios, for parliamentary television and in closed circuit television
15 systems.

Difficulties can arise in operating this known system, especially when a large number of camera positions are stored because the operator needs to be able to associate the camera position he requires with its respective shot code or number. Occasionally mistakes are made,
20 resulting in unintended pictures being transmitted.

In accordance with the present invention, for each stored camera position a respective picture associated with that camera position is stored; the stored pictures are displayed; and a required camera position is selected by selecting the respective displayed picture.
25 Accordingly, there is no need for the operator to remember shot codes or numbers, but merely to select a picture which represents the required output.

30 Preferably, the system is operable to determine when the camera, or the selected one of the cameras, has adopted its selected position, and then to replace the respective stored picture with the picture currently provided by that camera. Thus, if the system is used, for example, in a news broadcast studio, and if one of the stored positions has an associated picture showing the head and shoulders of a first newscaster, then if a second newscaster presents the next news bulletin, once that picture is selected and the camera has adopted the associated position, the stored picture of the head and shoulders of the first newscaster is replaced by a picture of the head and shoulders
35

of the second newscaster.

Preferably, a plurality of the stored pictures are displayed simultaneously, for example in a four-by-four array. In this case, picture selection can for example, be by means of a mouse or the like 5 or by using a touch-screen for the display. Additionally, or alternatively, the stored pictures can be paged on the display.

The system of the present invention may be used with a plurality of robotic cameras, and in this case in addition to storing each camera position, the identity of the camera which is selectively adopt that 10 position is also stored. In the case where a plurality of the stored pictures are displayed simultaneously, the system may have a first mode (which can be called "camera mode") in which all of the simultaneously displayed pictures relate to one camera. Additionally or alternatively, the system may have a second mode (which can be called 15 "story board mode") in which the simultaneously displayed pictures may relate to more than one of the cameras and in which selection of one of the pictures also serves to select the respective camera and the respective position.

Specific embodiments of the present invention will now be 20 described, by way of example, with reference to the accompanying drawings, in which:

Figure 1 is a schematic perspective view of a single camera system according to the invention;

Figure 2 is an example camera mode display screen;

25 Figure 3 is an example story board mode display screen; and

Figure 4 is a schematic perspective view of a multiple camera, dual control system according to the invention.

Referring to Figure 1, the system shown includes a control panel 10, an electronics unit 12, a robotic pedestal 14, a motorised pan and 30 tilt head 16 and a video camera 18. The control panel 10 and electronics unit 12 may be provided by an "advanced robotic control (ARC)" available from Radamec EPO. The pedestal 14 may be a "robotic pedestal (RP2)" available from Radamec EPO. The pan and tilt head 16 may be a "425 Pan & Tilt Head" as available from Radamec EPO. The 35 control panel 10 has various keys, knobs and joysticks and supplies signals via line 20 to the electronics unit 12, which in turn supplies signals via line 22 to cause the robotic pedestal to move as desired in

5 X and Y directions and to adjust the height of the camera, and also to cause the pan and tilt head 16 to adjust the pan and tilt of the camera, and optionally also the zoom and focus settings. The control panel 10 and electronics unit 12 can also store various position settings, and when a stored position is recalled, the camera 18 is moved to the stored position.

10 The system of Figure 1 also includes a personal computer 24 with an associated monitor 26 and mouse or other pointer device 28. The computer 24 may be a standard PC, but is fitted with one or more frame grabber cards, which are connected by line 30 to the video output of the camera 18. The computer 24 is also linked, for example via a serial I/O port and line 32, to the electronics unit 12.

15 The computer 24 is programmed so that the system operates as follows.

15

DISPLAY

20 The computer 24 causes the monitor 26 to display a screen 34 such as is shown in Figure 2. The screen contains, for example, a 4 x 4 array of sixteen shot areas, Shot A to Shot P, and also contains a menu bar 36 with such items as "store", "recall", "sequence" and "stop". Some of the shot areas may be blank, and when the system is first used all of the shot areas on the monitor will be blank.

POSITIONING

25

The camera 18 can be positioned, as in the conventional system, by manually operating the controls of the control panel 10, to adjust the X and Y positions and height of the camera, and also the pan and tilt, and focus and zoom settings.

30 **STORE**

35 Once a desired position of the camera has been adopted, that position can be stored. This is done by clicking the mouse on the "store" area of the menu bar 36 and then clicking the mouse on the desired shot area of the display. When this is done, firstly the current position of the camera is stored by the electronics unit 12 together with a shot code. Secondly, a frame of the video signal provided by the camera 18 is frame grabbed by the computer 24 and

1 stored in the computer memory along with the shot code. Thirdly, that
frame of video is displayed in reduced size at the appropriate shot
area on the monitor 26. In the case where the mouse is clicked on a
blank shot area, the new position data and the new frame of video data
5 are added to the memories in the electronics unit 12 and the computer
24. On the other hand, in the case where the mouse is clicked on a
previously occupied shot area, the previously stored position data and
frame of video data is overwritten with the new position data and frame
of video data.

10

RECALL

15 In order to cause the camera 18 to adopt a previously stored
position, firstly the mouse is clicked on "recall" on the display menu
bar 36, and then is clicked on the shot area of the display of the
desired camera position. The computer 24 determines the respective
shot code and commands the electronics unit 12 to move the camera to
the position stored by the electronics unit 12 for that shot code.
Accordingly, the electronics unit 12 drives the robotic pedestal 14 and
the motorised pan and tilt head 16 to cause the camera 18 to adopt the
20 selected position.

PAGING

25 As described above, in this specific embodiment, the monitor 26
can display up to 16 pictures simultaneously. The system may be
arranged to store more than 16 positions, and in this case, the shot
pictures are displayed on the monitor 26 in pages of 16 shot pictures,
and the operator can page the display by clicking the mouse on
"sequence" on the display menu bar 30, causing the pages of shot
pictures to cycle. Alternatively, the monitor 26 may display a single
30 shot picture, with the paging facility being used to cycle through the
stored shot pictures.

AUTOMATIC UPDATE

35 In a development of the system described above, the stored shot
pictures may be updated each time a position is recalled. Thus,
following on from the recall operation described above, when the camera
18 has adopted the selected position, a further frame of the video

signal is grabbed by the computer 24 and used to overwrite the previously stored video frame, but without changing the stored position data or the shot code. The freshly grabbed frame of video is then displayed in reduced size at the appropriate shot area on the monitor

5 26.

MULTIPLE CAMERAS

The arrangement shown in Figure 1 may be modified to include more than one camera 18, each with an associated robotic pedestal 14, pan and tilt head 16 and electronics unit 12. In this case, the electronics units 12 may be connected to a single control panel 10 and also to a single computer 24, and the video cameras 18 may be connected to respective frame grabber inputs of the computer 24. In this case, one of the cameras 18 can be selected, in conventional manner, from the 10 control panel 10, but additionally or alternatively, the menu bar 30 of the display 28 may include areas, such as "cam 1", "cam 2", "cam 3", "cam 4" on which the mouse can be clicked to select the appropriate camera. When one of the cameras is selected, the screen 34 displays 15 the stored shot pictures for the selected camera. When a position is to be stored, the mouse is clicked on "store" on the menu bar 36 and then on the desired shot area, and then not only is the position data stored by the respective electronics unit 12, but the computer 24 grabs a frame of video from the respective camera 18 and stores it, along 20 with not only the shot code, but also the identity of the camera for that shot. When a shot is recalled, the computer 24 commands the appropriate electronics unit 12 to position its camera 18, and 25 optionally when the camera is on position a fresh frame of video is grabbed from that camera and used to update the respective shot area.

30 ALTERNATIVE DISPLAY

Figure 3 shows an alternative screen 34 which may be displayed by the monitor 26. Like the screen of Figure 2, the Figure 3 screen has a 4 x 4 array of sixteen shot areas, but also has two menu bars 36a, 36b. The menu bar 36a has such items as "cut", "stop", "fade", 35 "store", "clear" and "recall", and the menu bar 36b has such items as "page up", "page down", "story board" and "clear all". Each shot area has an "on shot" indicator provided by a rectangle, for example, near

the top-left corner of the shot area, which may be illuminated to indicate that the respective camera is positioned for that shot. Also, the number (1-4) of the camera for each shot picture is displayed near the top-left corner of the shot area. The system can operate in a 5 "camera mode" and in a "story board mode". In order to select the story board mode, the mouse is clicked on "story board" on the menu bar 36b, and "story board" is then displayed in reverse video. In order to return to camera mode, the mouse is again clicked on "story board" and "story board" then reverts to normal video.

10

CAMERA MODE

In camera mode the displayed shot pictures all relate to the same camera. The required camera can be selected using the control panel 10.

15

CAMERA MODE - STORE

In order to store a new position, the selected camera is firstly moved to the desired position using the controls on the control panel 10. Once the desired position has been adopted, the mouse is clicked 20 on "store" on the menu bar 36a, which then turns to inverse video, and is then clicked on the desired shot area. The position and a shot code are then stored by the respective electronics unit 12. Also, a frame 25 of video from the respective camera 18 is grabbed and stored by the computer 24, together with the shot code and the camera number, and a reduced size form of the grabbed frame is displayed at the selected shot area and the associated on shot indicator is illuminated.

CAMERA MODE - RECALL

In order to recall a stored camera position when in camera mode, 30 firstly the required camera is selected, if necessary, using the control panel 10, and the screen 34 displays a first page of stored shot pictures for that camera. If more than sixteen shots have been stored, the operator can page through the stored shots by clicking the mouse on "page up" or "page down" on the menu bar 36b. Once the 35 desired shot picture is displayed, the mouse is then clicked on "recall" on the menu bar 36a, which then turns to inverse video. The mouse is then clicked on the desired shot area. The computer 24

commands the electronics unit 12 of the selected camera to move to the required position. Once the camera has adopted the required position, the respective on shot indicator is illuminated in the selected shot area and the video output is switched to the selected camera. This 5 switching may be effected as a "cut" or a "fade" depending upon which of "cut" and "fade" has been previously mouse-selected on the menu bar 36a, the selected item being displayed in inverse video. As with the previously described system, once the camera has adopted the required position, a fresh frame may be grabbed and used to update the stored 10 picture for that shot.

Also, once the selected camera has adopted its required position, "recall" on the menu bar 36a reverts to normal video.

STORY BOARD MODE

15 In story board mode, the screen 34 can display shot pictures for different cameras, and Figure 3 actually schematically represents a story board mode screen. In a four camera system it is therefore possible that up to four of the shot pictures can have their on shot indicators illuminated.

20

STORY BOARD MODE - STORE

The store operation in story board mode is similar to that in camera mode. That is to say, the desired camera is selected and positioned using the control panel 10 and then the mouse is clicked on 25 "store" and on the required shot position on the screen 34.

STORY BOARD MODE - RECALL

Recall in story board mode is also similar to that in camera mode, except that the required camera is not separately selected. 30 Instead, the selection of the camera takes place by way of the selection of the shot picture.

OTHER FACILITIES

Other facilities may be provided in the system. For example, in 35 order to clear one of the shot pictures and the associated stored data, the mouse is clicked on "clear" on the menu bar 36a and is then clicked on the shot area to be cleared. If all of the shots are to be cleared,

then the mouse is clicked on "clear" on the menu bar 36a and is then clicked on "clear all" on the menu bar 36b.

SYSTEM EXPANSION

5 The systems described above can be expanded to include a plurality of controls for one or more cameras. For example, Figure 4 shows a system having three cameras 18 each with its associated robotic pedestal 14, pan and tilt head 16 and electronics unit 12. Furthermore, two control panels 10 are provided, and two computers 24 10 are provided each with its associated monitor 26 and mouse 28.

OTHER MODIFICATIONS AND DEVELOPMENTS

It will be appreciated that many other modifications and developments may be made to the systems described above. For example, 15 it is possible to copy a shot picture from a camera mode page to a story board mode page. Also, rather than using a mouse 28 as the pointing device, it is possible to use a light pen or a touch screen monitor. Furthermore, it is possible to transfer the shot pictures and other data to other devices and use another such device to select a 20 camera position. For example, the computer 28 may be networked with one or more other computers. Also, a printer may be provided enabling the screens of shot pictures and other data to be printed out. Additionally, a further mode of operation may be provided in which each 25 row of shot pictures on the screen relates to a respective camera, and in which the shot pictures in a column can be selected simultaneously, causing up to, for example, four cameras to move to the associated positions simultaneously.

CLAIMS

1. A remote control system for one or more robotic cameras, comprising:
 - 5 means to store a plurality of camera positions;
 - means to select one of the stored camera positions; and
 - means to cause the camera or at least one selected one of the cameras to adopt the selected position;

characterised by:

 - 10 means to store for each stored camera position a respective picture associated with that camera position; and
 - means to display the stored pictures;
 - the position selecting means being operated by selecting the displayed picture for the position to be selected.
- 15 2. A system as claimed in claim 1, further comprising means to determine when the camera, or the selected one of the cameras, has adopted the selected position, and means to replace the respective stored picture with the picture currently provided by that camera.
- 20 3. A system as claimed in claim 1 or 2, wherein the display means is operable to display a plurality of the stored pictures simultaneously.
- 25 4. A system as claimed in any preceding claim, wherein the display means can be paged between at least one stored picture and at least one other stored picture.
- 30 5. A system as claimed in any preceding claim for use with a plurality of robotic video cameras, and further comprising means to store a camera identity for each stored camera position.
- 35 6. A system as claimed in claim 5 when dependent directly or indirectly on claim 3, further comprising means to select one of the cameras, and wherein the system is operable in a mode in which all of the simultaneously displayed pictures relate to the selected camera.
7. A system as claimed in claim 5 or 6 when dependent directly or

indirectly on claim 3, wherein the system is operable in a mode in which the simultaneously displayed pictures may relate to more than one of the cameras, and wherein selection of one of the pictures serves to select the respective camera and the respective position.

5

8. A remote control system for one or more robotic cameras, substantially as described with reference to the drawings.

Patents Act 1977**Examiner's report to the Comptroller under
Sect. 17 (The Search Report)**

Application number

9207079.6

Relevant Technical fields

(i) UK CI (Edition K) H4F FAA FCC

(ii) Int CL (Edition 5) H04N 5/232 5/247 7/18

Search Examiner

M K REES

Databases (see over)

(i) UK Patent Office

(ii) ONLINE DATABASE: WPI

Date of Search

28 APRIL 1992

Documents considered relevant following a search in respect of claims

1 TO 8

Category (see over)	Identity of document and relevant passages	Relevant to claim(s)
A	GB A 2235848 (JB MORGAN) See whole document	1
A	US 4566036 (CANON KK) See Figure 3; column 4, line 36 to column 5, line 36	1

Category	Identity of document and relevant passages	Relevant to claim(s)

Categories of documents

X: Document indicating lack of novelty or of inventive step.

Y: Document indicating lack of inventive step if combined with one or more other documents of the same category.

A: Document indicating technological background and/or state of the art.

P: Document published on or after the declared priority date but before the filing date of the present application.

E: Patent document published on or after, but with priority date earlier than, the filing date of the present application.

&: Member of the same patent family, corresponding document.

Databases: The UK Patent Office database comprises classified collections of GB, EP, WO and US patent specifications as outlined periodically in the Official Journal (Patents). The on-line databases considered for search are also listed periodically in the Official Journal (Patents).